

CLAIMS

1	(Unchanged) An apparatus for rotating a display orientation of captured
2	image data representative of an object, the apparatus comprising:
3	an image sensor, for generating said captured image data;
4	an orientation sensor coupled to said image sensor, for generating a signal
5	corresponding to the position of the image sensor relative to said
6	object;
7	a memory, having an auto-rotate unit comprising program instructions for
8	selectively transforming said captured image data into rotated im-
9	age data in response to said position signal, said memory coupled to
0	said image sensor and to said orientation sensor; and
1	an image processing unit coupled to said memory for executing program
2	instructions stored in said memory; and
3	an image capture unit generates an additional row and column of pixels
4	for said captured image data from said image sensor
5	[wherein (a) said image processing unit processes an i-by-j array of said captured
6	image data and said image sensor generates an i+1-by-j+1 array of said im-
7	age data, or (b) an image capture unit generates an additional row and col-
8	umn of pixels for said captured image data from said image sensor].
1	2. (As Filed) The apparatus of claim 1, wherein the memory further com-
2	prises:
3	an image processing unit comprising program instructions for transform-
4	ing one from a group consisting of captured image data and portrait
5	image data, into processed image data.

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3. (As Filed) The apparatus of claim is, wherein: the signal is a portrait_left signal if the image sensor is rotated clockwise from a landscape orientation relative to the object, and the signal is a portrait_right signal if the image sensor is rotated counter-clockwise from the landscape orientation relative to the object; and the auto-rotate unit comprises program instructions for transforming the captured image data into portrait_left image data in response to the portrait_left signal and into portrait_right image data in response to

4. (As Filed) The apparatus of claim 1, wherein:

the portrait_right signal.

the signal is a landscape signal if the image sensor is positioned in a level orientation relative to the object; and

the auto-rotate unit comprises program instructions for transforming the captured image data into landscape image data in response to the landscape signal.

5. (As Filed) The apparatus of claim 3, wherein:

the image sensor has a top, a bottom, a right side and a left side;
the auto-rotate unit program instructions transform the captured image
data into the portrait_left image data by transferring a prior portrait_left line of image data which starts further toward the bottom
of the image sensor and ends further toward the top of the image
sensor, then transferring a subsequent portrait_left line of image
data, located closer to the right side of the image sensor than the
prior portrait_left line of image data, and also starting further toward the bottom of the image sensor and ending further toward the
top of the image sensor; and

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the auto-rotate unit program instructions transform the captured image data into the portrait_right image data by transferring a prior portrait_right line of image data which starts further toward the top of the image sensor and ends further toward the bottom of the image sensor, then transferring a subsequent portrait_right line of image data, located closer to the left side of the image sensor than the prior portrait_right line of image data, and also starting further toward the top of the image sensor and ending further toward the bottom of the image sensor.

6. (As Filed) The apparatus of claim 4, wherein:

the image sensor has a top, a bottom, a right side and a left side; and the auto-rotate unit program instructions transform the captured image data into the landscape image data by transferring a prior landscape line of image data which starts further toward the left side of the image sensor and ends further toward the right side of the image sensor, then transferring a subsequent landscape line of image data, located closer to the bottom of the image sensor than the prior landscape line of image data, and also starting further toward the left side of the image sensor and ending further toward the right side of the image sensor.

7. (As Filed) The apparatus of claim 3, wherein:

the portrait_left signal is generated by the orientation sensor if the image sensor is rotated approximately 45° clockwise from the level orientation, and the portrait_right signal is generated by the orientation

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5	sensor if the imaging subsystem is rotated approximately 45°
6	counter-clockwise from the level orientation.
1	8. (As Filed) The apparatus of claim 5, wherein:
2	the prior portrait_left line of image data and the prior portrait_right line o
3	image data comprise a "green, red, green, red" pixel pattern; and
4	the subsequent portrait_left line of image data and the subsequent por-
5	trait_right line of image data comprise a "blue, green, blue, green"
6	pixel pattern.
1	9. (As Filed) An apparatus for rotating a display orientation of multicolor
2	captured image data having an i-by-j pixel matrix with a pattern representative of ar
3	object, comprising:
4	an image sensor, for generating the multicolor captured image data;
5	an input device, for generating a portrait_left signal in response to a first
6	user selection, a portrait_right signal in response to a second user
7	selection, and a landscape signal in response to a third user selec-
8	tion;
9	a memory, having:
10	an auto-rotate unit comprising program instructions for selec-
11	tively transforming the multicolor captured image data
12	into portrait_left image data in response to the portrait-
13	left signal, portrait_right image data in response to the
14	portrait_right signal, and landscape image data in re-
15	sponse to the landscape signal; and
16	an image processing unit comprising program instructions for
17	transforming the portrait_left image data, the por-

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trait_right image da	ta and the landscape image data into
processed image da	ta; and

- a processing unit, coupled to the image sensor, to the input device, and to the memory, for executing program instructions stored in the memory;
- wherein said image processing unit changes the number of pixel rows and pixel columns of the multicolor captured image data such that, from a defined referenced viewpoint, the portrait left image data, the portrait right image data, and the landscape image data, each includes an (i-1)-by-(j-1) pixel matrix having said pattern.
- 10. (As Filed) The apparatus of claim 9, wherein the image processing unit
 2 has a first line length for processing the portrait_left image data and the por3 trait_right image data and a second line length for processing the landscape image
 4 data.
 - 11. (Unchanged) A method for rotating a display orientation of image data representative of an object, comprising the steps of:
- 3 generating image data with an image sensor;

identifying step;

- identifying an orientation of the image sensor relative to the object at a

 time substantially simultaneous with the generating step, where

 said identifying is performed by an orientation sensor; and

 selectively transferring data to an image processing unit in response to the
- [wherein said image processing unit rotates said display orientation of said image data and (a) said image processing unit processes an i-by-j array of said captured image data and said image sensor generates an i+1-by-j+1 array

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of said image data, or (b) an im	age capture unit generates an additional row
and column of pixels for said c	aptured image data from said image sensor]
wherein said image processing uni	rotates said orientation of said image
data by generating an additi	onal row and column of pixels for said
captured image data from sa	id image sensor.

12. (Cancelled)

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13. (As Filed) The method of claim 11, further comprising the step of correcting defects within the image data caused by defects within the image sensor.

14. (As Filed) The method of claim 11, wherein the image sensor comprises a top, a right side and a left side, wherein the image comprises a "top portion," and wherein the step of identifying an orientation further comprises the steps of:

identifying a portrait_left orientation, if the left side of the image sensor corresponds to the "top portion" of the object;

identifying a portrait_right orientation, if the right side of the image sensor corresponds to the "top portion" of the object; and identifying a landscape orientation, if the top of the image sensor corresponds to the "top portion" of the object.

entation further comprises the steps of identifying a portrait_left orientation, in response to a user selection of the portrait_left orientation on an input device; identifying a portrait_right orientation, in response to a user selection of the portrait_right orientation on the input device; and

15. (As Filed) The method of claim 11, wherein the step of identifying an ori-

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identifying a landscape orientation, in response to a user selection of the

landscape orientation on the input device.

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	1	16. (As Filed) The method of claim 11, wherein the orientation is a por-
7.16	2	trait_left orientation, wherein the image data is comprised of an array of pixel colors
4, W.	3	ordered in rows and columns, and wherein the step of selectively transferring com-
U	4	prises the steps of:
	5	initializing a column variable to a first column of pixel colors required by
	6	the image processing unit;
. \	7	initializing a row variable to a row containing a first pixel color required
J, 24	8	by the image processing unit;
C	9	transferring pixel color at an array location defined by the row variable
	10	and the column variable to the image processing unit;
	11	decrementing the row variable to a row containing a next pixel color re-
	12	quired by the image processing unit;
	13	returning to the transferring step, if a row containing a last pixel color has
	14	not been transferred;
	15	incrementing the column variable to a next column of pixel colors required
	16	by the image processing unit; and
	17	returning to the initializing a row variable step, if a last column of pixel
	18	colors has not been transferred.

18. (As Filed) The method of claim 16, further comprises the steps of:

defective image sensor information, further comprising the step of repeating the

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steps of claim 16.

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17. (As Filed) The method of claim 16, wherein the image data is replaced by

2	configuring the image processing unit to accept an image data line length
3	corresponding to the portrait_left orientation; and
4	performing image processing on a line of transferred image data.
1	19. (As Filed) The method of claim 11, wherein the orientation is a por-
2	trait_right orientation, wherein the image data is comprised of an array of pixel col-
3	ors ordered in rows and columns, and wherein the step of selectively transferring
4	comprises the steps of:
5	initializing a column variable to a first column of pixel colors required by
6	the image processing unit;
7	initializing a row variable to a row containing a first pixel color required
8	by the image processing unit;
9	transferring pixel color at an array location defined by the row variable
10	and the column variable, to the image processing unit;
17	incrementing the row variable to a row containing a next pixel color re-
12	quired by the image processing unit;
13	returning to the transferring step, if a row containing a last pixel color has
14	not been transferred;
15	decrementing the column variable to a next column of pixel colors re-
16	quired by the image processing unit; and
17	returning to the initializing a row variable step, if a last column of pixel
18	colors has not been transferred.
1 .	20. (As Filed) The method of claim 11, wherein the orientation is a landscape
2	orientation, wherein the image data is comprised of an array of pixel colors ordered
3	in rows and columns, and wherein the step of selectively transferring comprises the
4	steps of:

age processing unit;

quired by the image processing unit;

required by the image processing unit;

has not been transferred;

image processing unit; and

colors has not been transferred.

age data having a Bayer pattern;

initializing a row variable to a first row of pixel colors required by the im-

initializing a column variable to a column containing a first pixel color re-

transferring pixel color at an array location defined by the row variable

incrementing the column variable to a column containing a next pixel color

returning to the transferring step, if a column containing a last color pixel

incrementing the row variable to a next row of pixel colors required by the

returning to the initializing a column variable step, if a last row of pixel

(Amended) An apparatus for rotating a display orientation of multicolor

means for generating multicolor image data with an image sensor, the im-

orientation sensor means for identifying an orientation of said image sen-

means for selectively transferring said multicolor image data to an image

wherein said image processing unit rotates said display orientation of said

multicolor image data for providing rotated multicolor image data,

processing unit in response to said means for identifying;

sor relative to said object at a time substantially simultaneous with

image data having an i-by-j pixel matrix with a pattern representative of an object,

said generating said multicolor image data; and

and the column variable, to the image processing unit;

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comprising:

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and changes the number	of pixel rows and pixel columns of said
multicolor image data su	ch that, from a defined referenced view-
point, said rotated multi	color image data includes an (i-1)-by-(j-1)
pixel matrix having said	pattern.

- 22. (As Filed) The apparatus of claim 21, further comprising means for generating an additional row and column of image data.
- 23. (As Filed) The apparatus of claim 21, further comprising means for correcting defects within the image data caused by defects within the image sensor.
- 24. (As Filed) The apparatus of claim 21, wherein the image sensor comprises a top, a right side and a left side, wherein the image comprises a "top portion," and wherein the means for identifying an orientation further comprises:
 - means for identifying a portrait_left orientation, if the left side of the image sensor corresponds to the "top portion" of the object; means for identifying a portrait_right orientation, if the right side of the image sensor corresponds to the "top portion" of the object; and means for identifying a landscape orientation, if the top of the image sensor corresponds to the "top portion" of the object.
- 25. (As Filed) The apparatus of claim 21, wherein the orientation is a portrait_left orientation, wherein the image data is comprised of an array of pixel colors ordered in rows and columns, and wherein the means for selectively transferring comprises:
- means for initializing a column variable to a first column of pixel colors required by the image processing unit;

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means for initializing a row variable to a row containing a first pixel color
required by the image processing unit;
means for transferring pixel color at an array location, defined by the row
variable and the column variable, to the image processing unit;
means for decrementing the row variable to a row containing a next pixel
color required by the image processing unit;
means for returning to the means for transferring, if a row containing a last
pixel color has not been transferred;
means for incrementing the column variable to a next column of pixel col-
ors required by the image processing unit; and
means for returning to the means for initializing a row variable, if a last
column of pixel colors has not been transferred.
26. (As Filed) The apparatus of claim 21, wherein the orientation is a por-
trait_right orientation, wherein the image data is comprised of an array of pixel col-
ors ordered in rows and columns, and wherein the means for selectively transferring
comprises:
means for initializing a column variable to a first column of pixel colors re-
quired by the image processing unit;
means for initializing a row variable to a row containing a first pixel color
required by the image processing unit;
means for transferring pixel color at an array location, defined by the row
variable and the column variable, to the image processing unit;

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means for incrementing the row variable to a row containing a next pixel

means for returning to the means for transferring, if a row containing a last

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color required by the image processing unit;

pixel color has not been transferred;

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means for decrementing the column variable to a next column of pixel colors required by the image processing unit; and means for returning to the means for initializing a row variable, if a last column of pixel colors has not been transferred.

27. (As Filed) The apparatus of claim 21, wherein the orientation is a land-scape orientation, wherein the image data is comprised of an array of pixel colors ordered in rows and columns, and wherein the means for selectively transferring comprises:

means for initializing a row variable to a first row of pixel colors required by the image processing unit;

means for initializing a column variable to a column containing a first pixel color required by the image processing unit;

means for transferring pixel color at an array location, defined by the row variable and the column variable, to the image processing unit; means for incrementing the column variable to a column containing a next pixel color required by the image processing unit;

means for returning to the means for transferring, if a column containing a last color pixel has not been transferred;

means for incrementing the row variable to a next row of pixel colors required by the image processing unit; and

means for returning to the means for initializing a column variable, if a last row of pixel colors has not been transferred.

28. (Amended) A computer useable medium embodying computer readable program code for causing a computer to rotate a display orientation of multicolor

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3	image data having an i-by-j pixel matrix with a pattern representative of an object, by
4	performing steps comprising:
5	generating said multicolor image data with an image sensor, the image
6	data having a Bayer pattern
7	identifying an orientation of the image sensor relative to the object at a
8	time substantially simultaneous with the generating step, wherein
9	said identifying of said orientation is performed with an orientation
10	sensor; and
11	selectively transferring image data to an image processing unit in response
12	to the identifying step,
13	wherein said image processing unit rotates said display orientation of said
14	multicolor image data for providing rotated multicolor image data,
15	and changes the number of pixel rows and pixel columns of said
16	multicolor image data such that, from a defined referenced view-
17	point, said rotated multicolor image data includes an (i-1)-by-(j-1)
18	pixel matrix having said pattern.
_	
1	29. (As Filed) The computer useable medium of claim 28, further comprising
2	program code for generating an additional row and column of image data.
1	30. (As Filed) The computer useable medium of claim 28, further comprising
2	program code for correcting defects within the image data caused by defects within
3	the image sensor.
1	31. (As Filed) The computer useable medium of claim 28, wherein the image
2	sensor comprises a top, a right side and a left side, wherein the image comprises a
3	"top portion," and wherein the program code for performing the step of identifying
4	an orientation further comprises program code for:

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6	corresponds to the "top portion" of the object;
7	identifying a portrait_right orientation, if the right side of the image sensor
8	corresponds to the "top portion" of the object; and
9	identifying a landscape orientation, if the top of the image sensor corre-
10	sponds to the "top portion" of the object.
1	32. (As Filed) The computer useable medium of claim 28, wherein the orien-
2	tation is a portrait_left orientation, wherein the image data is comprised of an array
3	of pixel colors ordered in rows and columns, and wherein the program code for per-
4	forming the step of selectively transferring comprises program code for:
5	initializing a column variable to a first column of pixel colors required by
6	the image processing unit;
7	initializing a row variable to a row containing a first pixel color required
8	by the image processing unit;
9	transferring pixel color at an array location, defined by the row variable
10	and the column variable, to the image processing unit;
11	decrementing the row variable to a row containing a next pixel color re-
12	quired by the image processing unit;
13	returning to the transferring step, if a row containing a last pixel color has
14	not been transferred;
15	incrementing the column variable to a next column of pixel colors required
16	by the image processing unit; and
17	returning to the initializing a row variable step, if a last column of pixel

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4	55. (As riled) The computer useable medium of claim 28, wherein the orien-
2	tation is a portrait_right orientation, wherein the image data is comprised of an array
3	of pixel colors ordered in rows and columns, and wherein the program code for per-
4	forming the step of selectively transferring comprises program code for:
5	initializing a column variable to a first column of pixel colors required by
6	the image processing unit;
7	initializing a row variable to a row containing a first pixel color required
8	by the image processing unit;
9	transferring pixel color at an array location, defined by the row variable
10	and the column variable, to the image processing unit;
11	incrementing the row variable to a row containing a next pixel color re-
12	quired by the image processing unit;
13	returning to the transferring step, if a row containing a last pixel color has
14	not been transferred;
15	decrementing the column variable to a next column of pixel colors re-
16	quired by the image processing unit; and
17	returning to the initializing a row variable step, if a last column of pixel
18	colors has not been transferred.
1	34. (As Filed) The computer useable medium of claim 28, wherein the orien-
2	tation is a landscape orientation, wherein the image data is comprised of an array of
3	pixel colors ordered in rows and columns, and wherein the program code for per-
4	forming the step of selectively transferring comprises program code for:
5	initializing a row variable to a first row of pixel colors required by the im-
6	age processing unit;

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	7	initializing a column variable to a column containing a first pixel color re-
	8	quired by the image processing unit;
	9	transferring pixel color at an array location, defined by the row variable
	710	and the column variable, to the image processing unit;
7.40) 11	incrementing the column variable to a column containing a next pixel color
· U	12	required by the image processing unit;
	13	returning to the transferring step, if a column containing a last color pixel
	14	has not been transferred;
	15	incrementing the row variable to a next row of pixel colors required by the
11.7	. 16	image processing unit; and
C, Ca	17	returning to the initializing a column variable step, if a last row of pixel
	18	colors has not been transferred.
	3	35. (Amended) An apparatus for rotating a display orientation of multicolor
	2	captured image data having an i-by-j pixel matrix with a pattern representative of an
	3	object, comprising:
	4	an image sensor, for generating said multicolor captured image data, the
	5	image data having a Bayer pattern;
	6	an orientation sensor coupled to said image sensor, for generating a signal
	7	corresponding to the position of said image sensor relative to said

object; and

tion sensor;

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a hardware device, having an auto-rotate unit comprising circuits for selec-

multicolor image data in response to said position signal, said

tively transforming said multicolor captured image data into rotated

hardware device coupled to said image sensor and to said orienta-

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14	wherein, from a defined referenced viewpoint, said rotated multicolor im-				
15	age data includes an $(i / 1)$ -by- $(j-1)$ pixel matrix having said pattern.				
	36. (Unchanged) An apparatus for rotating a display orientation of captured				
	image data representative of an object, the apparatus comprising:				
4 P	an image sensor, for generating said captured image data;				
4	an input device, for generating an orientation signal in response to a user				
, 5	selection;				
6	a memory, having an auto-rotate unit for selectively transforming said cap-				
1.1.	tured image data into rotated image data in response to said orien-				
i or s	tation signal from said input device; and				
an image processing unit coupled to said memory for processing the independent of the ind					
				1	37. (Twice Amended) A digital image capture device, comprising:
2	an image sensor, for capturing image data;				
3	an orientation sensor, for generating an orientation signal indicating				
4	whether the image sensor is in a portrait or landscape position; and				
5	5 an auto-rotate unit coupled to the image sensor and the orientation sensor,				
6	for automatically rotating a subset of the image data in response to				
7	7 the orientation signal.				
1	38. (Cancelled)				
1	39. (Unchanged) The digital image capture device of claim 37, further com-				
2	prising:				

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	j	an image capture unit coupled to the image sensor, for adding m addi-			
	4	tional tows and n additional columns to an i-by-j array of image			
	5	data to form an i+m-by i+n array of image data to be rotated by the			
	6	auto-rotate unit in response to the orientation signal.			
	1	40. (Twice Amended) A method of rotating image data in a digital image			
•	2	capture device, comprising:			
	3	capturing image data from an image sensor;			
	4	providing an orientation signal indicating whether the image sensor is in a			
	5	portrait or landscape position; and automatically rotating a subset of the captured image data in response to			
•	6				
	7	the orientation signal.			
	, 1	41. (Cancelled)			
	1	42. (Unchanged) The method of claim 40, further comprising:			
	2	adding m additional rows and n additional columns to an i-by-j array of			
	3	the image data to form an i+m-by-j+n array of image data.			
	1	43. (Twice Amended) A computer-readable medium having stored thereon			
	2	instructions which, when executed by a processor, cause the processor to perform the			

steps of: 3

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capturing image data from an image sensor:

providing an orientation signal indicating whether the image sensor is in a

portrait or landscape orientation; and

automatically rotating a subset of the captured image data in response to

the orientation signal.

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	1	44. (Cancelled)
20,0	1	45. (Unchanged) The computer-readable medium of claim 43, further com-
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U	3	adding m additional rows and n additional columns to an i-by-j array of
	4	the image data to form an i+m-by-j+n array of image data.
4.1	7	46. (Amended Three Times) A digital image capture device, comprising:
r cr	2	image sensor means for generating image data:
	3	means for generating an orientation signal indicating either a portrait ori-
	4	entation or a landscape orientation of the image sensor; and
	5	means for automatically rotating a subset of the image data in response to
	6	the orientation signal.
	1	47. (Unchanged) A digital image capture device, comprising:
	2	an image sensor, for generating said captured image data including a plu-
	3	rality of rows and columns of pixels;
	4	an orientation sensor coupled to said image sensor, for generating a posi-
	5	tion signal indicating whether the image sensor is in a portrait or
	6	landscape position:
	7	a memory, having an auto-rotate unit comprising program instructions fo
	8	selectively transforming said captured image data into rotated im-
	9	age data in response to said position signal by processing at least
	10	one row of pixels and at least one column of pixels less than the plu
	11	rality of rows and columns of pixels in the captured image data,
	12	said memory coupled to said image sensor and to said orientation
	13	sensor; and
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14	an image processing unit cou	upled to said memory for executing the stored
15	program instructions t	to rotate said capture image data.
1	48. (Unchanged) A method for	rotating a display orientation of image data,
\ \\ \\ 2	comprising:	
U, Cay, 3	generating image data with a	n image sensor including a plurality of rows
4	and columns of pixels;	<u>.</u>
5	determining with an orientati	ion sensor a portrait orientation or a land-
6	scape orientation for the	he image data substantially simultaneously
7	with generating the im	nage data; and
8	processing the image data wi	th an image processing unit in response to the
9	orientation signal to ro	otate the image data, by rotating less than all
10	of the plurality of rows	s and columns of pixels of the image data.